

# C++ Concurrency

## future<RetType>

**RetType | RetType& | void get()**  
get the result - blocks until result is ready; return type determined by *RetType* template parameter

**bool valid()**  
true if *get* hasn't been called

**shared\_future<RetType> share()**  
convert *future* to *shared\_future*

**void wait()**  
block until result is available

**future\_status wait\_for(const duration&)**  
wait for the result for a specified period; unblock when result is available or after duration elapsed

**future\_status wait\_until(const time\_point&)**  
wait for the result until the specified point in time; unblock when result is available or when time point passed

## shared\_future<RetType>

**shared\_future(future<RetType>&&)**  
move-construct from a *future*

**RetType | RetType& | void get()**  
get the result - blocks until result is ready; return type determined by *RetType* template parameter

**bool valid()**  
true if *get* hasn't been called







**shared\_future<RetType> share()**  
convert *future* to *shared\_future*

**void wait()**  
block until result is available

**future\_status wait\_for(const duration&)**  
wait for the result for a specified period; unblock when result is available or after duration

**future\_status wait\_until(const time\_point&)**  
wait for the result until the specified point in time

## Legend

 default constructor	 copy assignment operator
 copy constructor	 move assignment operator
 move constructor	 swap method



## thread

**thread<F, Args...>(F&&, Args&&...)**  
construct from *F* and *Args*

**bool joinable()**  
true if the thread hasn't been detached

**void join()**  
block until thread completes

**void detach()**  
give up control of the thread

**id get\_id()**  
get thread ID

**native\_handle\_type native\_handle()**  
get platform specific thread handle

**static unsigned hardware\_concurrency()**  
return an estimate of hardware thread contexts

## this\_thread namespace

**thread::id get\_id()**  
return the unique ID of the calling thread

**void yield()**  
offer the implementation a chance to reschedule

**void sleep\_until(const time\_point&)**  
block the calling thread until specified time

**void sleep\_for(const duration&)**  
block the calling thread for specified period

## Free functions

**future<RetTypeOfF> async([launch], F&&, Args&&...)**  
return a future and execute *F* with *Args* according to launch policy if provided, or with *launch::async* | *launch::deferred* otherwise

**void lock<L1, L2, L3...>(L1&, L2&, L3&...)**  
lock all arguments using a deadlock avoidance algorithm; in case of failure, unlock all previously locked arguments and return

**int try\_lock<L1, L2, L3...>(L1&, L2&, L3&...)**  
call *try\_lock* on each argument in order & return -1; if an argument can't be locked, unlock all previous arguments & return its index

**void call\_once(once\_flag&, F&&, Args&&...)**  
execute *F* with *Args* only once in a multi-threaded context

## lock\_guard<Mutex>

**lock\_guard(Mutex&, [adopt\_lock\_t])**  
lock the mutex on construction and release on destruction

## packaged\_task<RetType, ArgTypes...>

**packaged\_task<F>(F&&)**  
**packaged\_task<F, Alloc>(allocator\_arg\_t, const Alloc&, F&&)**  
construct from *F*, using *Alloc* for internal data structures (if provided)

**future<RetType> get\_future()**  
return a future for this task

**void operator()(ArgTypes...)**  
execute the task and signal the future

**bool valid()**  
*true* if the task has shared state

**void make\_ready\_at\_thread\_exit(ArgTypes...)**  
execute the task and signal the future at thread exit

**void reset()**  
construct new shared state, abandon old state

## promise<RetType>

**promise<Alloc>(allocator\_arg\_t, const Alloc&)**  
construct using *Alloc* for shared state

**future<RetType> get\_future()**  
return a future for this promise

**void set\_value(const RetType&)**  
**void set\_value(RetType&& | RetType& | void)**  
set the result and signal the future

**void set\_exception(exception\_ptr)**  
set an exception and signal the future

**void set\_value\_at\_thread\_exit(const RetType&)**  
**void set\_value\_at\_thread\_exit(RetType&& | RetType& | void)**  
set result and signal the future at thread exit

**void set\_exception\_at\_thread\_exit(exception\_ptr)**  
set exception and signal the future at thread exit

## unique\_lock<Mutex>

**unique\_lock(Mutex&, [defer\_lock\_t | try\_to\_lock\_t | adopt\_lock\_t])**  
possibly acquire mutex on construction

**mutex\_type\* release()**  
unlock and return a pointer to mutex

**bool owns\_lock()**  
*true* if the mutex is locked

**mutex\_type\* mutex()**  
return a pointer to mutex

Also has the same methods as *timed\_mutex* (except *native\_handle*)

## condition\_variable

**void notify\_one()**  
unblock one of the waiting threads

**void notify\_all()**  
unblock all of the waiting threads

**void wait(unique\_lock<mutex>&, [Predicate])**  
unlock the mutex and block the thread until the condition variable is signalled; use *Predicate* to check for spurious wakeups

**cv\_status | bool wait\_until(unique\_lock<mutex>&, const time\_point&, [Predicate])**  
like *wait*, but only wait until specified time point; return *cv\_status* or, if *Predicate* is supplied, the value of *Predicate*

**cv\_status | bool wait\_for(unique\_lock<mutex>&, const duration&, [Predicate])**  
like *wait*, but only wait for the specified duration; return *cv\_status* or, if *Predicate* is supplied, the value of *Predicate*

**native\_handle\_type native\_handle()**  
get platform specific handle

## condition\_variable\_any

Same interface as *condition\_variable*, but *wait\** methods allow a custom lock class in place of *unique\_lock*, and *native\_handle* method isn't available

## mutex/recursive\_mutex

**void lock()**  
*recursive\_mutex* allows multiple calls to *lock* with increasing levels of ownership

**bool try\_lock()**  
immediately return *false* if unable to lock

**void unlock()**

**native\_handle\_type native\_handle()**  
get platform specific handle

## timed\_mutex/ recursive\_timed\_mutex

Same as *mutex/recursive\_mutex*, with two extra methods:

**bool try\_lock\_for(const duration&)**  
try to lock for the specified duration

**bool try\_lock\_until(const time\_point&)**  
try to lock until the specified time point